

$$Y(f) = H(f) \cdot X(f)$$

multiplication in frequency

is

$$y(t) = \int_{-\infty}^{+\infty} h(\tau) x(t-\tau) d\tau$$

convolution in time

need phase information besides the gain for $H(f) = \int_{-\infty}^{+\infty} h(\tau) e^{-j2\pi f\tau} dt$

Consider cross-covariance

unknown

$$x(t) y(t+\tau) = \int_{-\infty}^{+\infty} x(t) h(\alpha) x(t+\tau-\alpha) d\alpha$$

Take expected value where x, y are measurement and h are unknown, but fixed weights

note that integral does not involve integration of time t , but convolution α

$$E[x(t) y(t+\tau)] = \int_{-\infty}^{+\infty} h(\alpha) E[x(t) x(t+\tau-\alpha)] d\alpha$$

$$R_{xy}(\tau) = \int_{-\infty}^{+\infty} h(\alpha) R_{xx}(\tau-\alpha) d\alpha$$

Take the Fourier Transform of both sides

$$\int_{-\infty}^{+\infty} R_{xy}(\tau) e^{-j2\pi f\tau} d\tau = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} h(\alpha) R_{xx}(\tau-\alpha) d\alpha e^{-j2\pi f\tau} d\tau$$

↳

$$S_{xy}(f) = \iint_{-\infty}^{+\infty} h(\alpha) R_{xx}(q) d\alpha e^{-j2\pi f\alpha} \cdot e^{-j2\pi f(q-\alpha)} dq d\alpha$$

$$q = \tau - \alpha \quad \frac{dq}{d\tau} = 1 \quad \tau = q + \alpha$$

↳

$$S_{xy}(f) = \int_{-\infty}^{+\infty} h(\alpha) e^{-j2\pi f\alpha} d\alpha \cdot \int_{-\infty}^{+\infty} R_{xx}(q) e^{-j2\pi fq} dq$$

↳

$$S_{xy}(f) = H(f) \cdot S_{xx}(f) \quad \text{two-side spectra}$$

$$G_{xy}(f) = H(f) \cdot G_{xx}(f) \quad \text{one-sided spectra}$$

$$\text{or} \quad |G_{xy}(f)| e^{-j\Theta_{xy}(f)} = |H(f)| e^{-j\phi(f)} \underbrace{G_{xx}(f)}_{\text{real}}$$

↳

$$(1) \quad \Theta_{xy}(f) = \phi(f) \quad \text{transfer function } H \text{ has phase of the cross-spectrum } G_{xy}$$

$$(2) \quad \frac{|H(f)|}{G_{xx}(f)} = \frac{G_{xy}(f)}{G_{xx}(f)} = \Gamma_{xy}^2 \cdot G_{yy}$$

We are talking about ideal systems, not estimates, and as long as

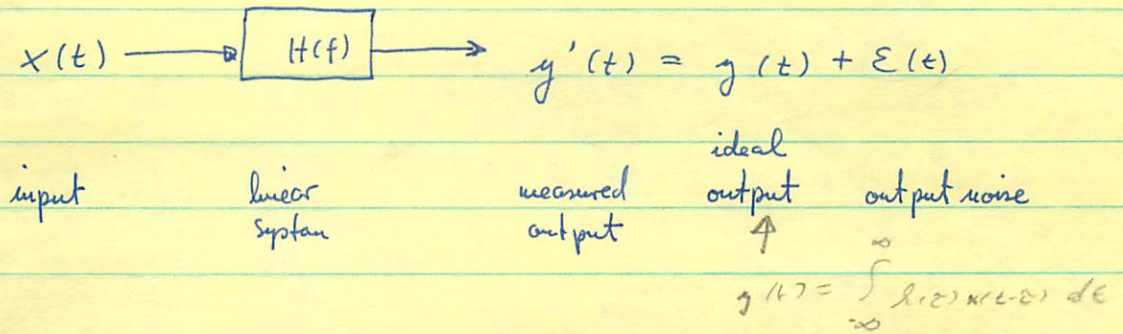
$$G_{xx} \neq 0 \neq G_{yy}$$

the coherence $\Gamma_{xx}^2 = 1$

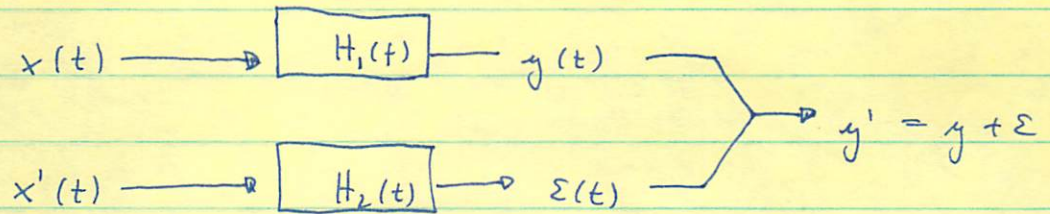
Otherwise, i.e., $G_{xx} = 0$ or $G_{yy} = 0$ it would be 0

A more realistic system, however, is one that is slightly imperfect, i.e.

CASE 1



(a) where ϵ is noise or, possibly, contributions from another linear (or nonlinear) system:



(b) where ϵ is random or white noise (most pleasant)

(c) where ϵ originates from nonlinear processes

If $\Sigma(t)$ is random or pure white noise, then

$$G_{x\varepsilon}(t) = G_{y\varepsilon}(t) = 0$$

this condition
can be relaxed
to allow correlated

Now

$$\begin{aligned} G_{y'y'} &= \frac{2}{T} (Y + \Sigma) (Y^* + \Sigma^*) \\ &= \frac{2}{T} (Y Y^* + \cancel{Y \Sigma^*} + \cancel{Y^* \Sigma} + \Sigma \Sigma^*) \\ &= G_{yy} + G_{\varepsilon\varepsilon} \end{aligned}$$

output noise however
the same results can be derived
if the relevant
transfer function
is interpreted as
a least squares
estimate of the
transfer function that
minimises the output
noise

$$\Gamma_{xy'}^2 = \frac{|G_{xy'}|^2}{G_{xx} G_{y'y'}} = \frac{X^* (Y + \Sigma) \cdot X (Y^* + \Sigma^*)}{X X^* (Y^* + \Sigma^*) (Y + \Sigma)}$$

see p.105

$$= \frac{(G_{xy} + G_{x\varepsilon}) \cdot (G_{xy}^* + G_{x\varepsilon}^*)}{G_{xx} (G_{yy} + G_{\varepsilon\varepsilon})}$$

$$= \frac{|G_{xy}|^2}{G_{xx} G_{yy} + G_{xx} G_{\varepsilon\varepsilon}}$$

$$= \frac{|G_{xy}|^2}{G_{xx} G_{yy}} \frac{1}{1 + G_{\varepsilon\varepsilon} / G_{yy}}$$

$$= \frac{\Gamma_{xy}^2}{1 + \frac{G_{\varepsilon\varepsilon}}{G_{yy}}} \stackrel{\Gamma_{xy}^2 = 1}{=} \frac{G_{yy}}{G_{yy} + G_{\varepsilon\varepsilon}} = \frac{G_{yy}}{G_{y'y'}}$$

linear system

$$\Gamma_{xy'}^2 = \frac{|G_{xy'}|^2}{G_{xx} \cdot G_{y'y'}} = \frac{G_{yy}}{G_{y'y'}}$$

= $\frac{\text{variance @ frequency } f \text{ that is due to the}}{\text{variance @ frequency } f \text{ that is due to}}$
 both noise and linear system

where $x(t)$ measured input
 $y'(t)$ measured "noisy" output, i.e., $y'(t) = y(t) + \epsilon(t)$
 $y(t)$ output due to "forcing" by input; i.e., part of the measured output that is linearly related to input
 $\epsilon(t)$ noise that is uncorrelated with both input $x(t)$ and output $y(t)$

$\Gamma_{xy'}^2$ coherence between input $x(t)$ and measured noisy output $y'(t)$
 G_{xx} one-sided cross-spectrum between measured input and measured noisy output
 $G_{y'y'}$ one-sided auto-spectrum ~~between~~ of the measured noisy input
 G_{yy} one-sided auto-spectrum of the "clean" unmeasured output produced by the linear system; this property can not be computed directly but through the coherence fn. ^{output}

$\Rightarrow \Gamma_{xy'}^2$ is the fraction of the ^{output} variance that is ~~due to the linear~~ system can be explained ~~by~~ a linear system by the input through

examples/applications

Fig-10 p. 486 of Thomson et al (1992) → (1) astronomical and nonlinear tides; remove the "wind" forcing
 (2) barotropic vs. baroclinic tides; keep the seawall coherent part

Fig-3 p. 566 of Thomson (1998)



part II
of class 13

"Statistics" of $\hat{\Gamma}_{xy}^2(f)$

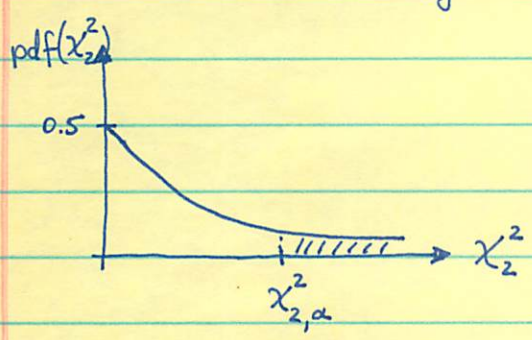
for large degrees of freedom d.o.f.
i.e., d.o.f > 40

1. Hypothesis testing; Confidence levels

Hypothesis: $x(t)$ and $y(t)$ are independent, i.e., $\hat{\Gamma}_{xy}^2 = 0$

For large d.o.f. n an empirical result is that

$$n \cdot \hat{\Gamma}_{xy}^2 \approx \chi_2^2$$



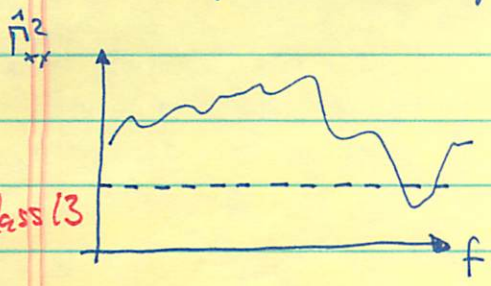
there is an α % chance
that $n \hat{\Gamma}_{xy}^2 > \chi_{2,\alpha}^2$

$$\text{Prob} \left[\hat{\Gamma}_{xy}^2 > \frac{\chi_{2,\alpha=0.05}^2}{n} \right] = 0.05 = \alpha$$

$\chi_{2,0.05}^2 \cong 6$
↳ 95% confidence level
from $\frac{6}{n}$
i.e., $\hat{\Gamma}_{xy}^2 > \frac{6}{n}$ ↳ 95% chance
to be different
from 0

This represents a significance level, not a confidence interval

end of class 13



95% level of coherence } 95% chance of $\hat{\Gamma}_{xy}^2$ to
be significantly different from 0
5% — " —

Go to p.-92 " Multiple Input - Single Output