

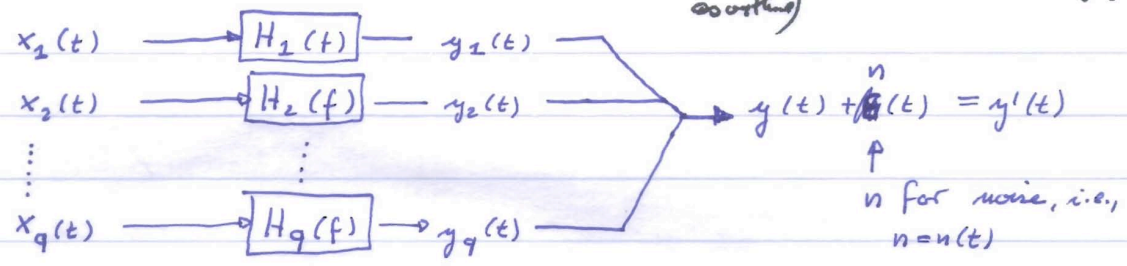
Hence we got  $N$  linear equations to solve for the  $N$  unknown signal to noise ratios  $^2/c_i$   $i=1,2,\dots,N$

input may be correlated

Multiple input / single output

(started with p. 98 outline)

$$\left\{ \begin{aligned} G_{xy} &= H \cdot G_{xx} \\ H &= G_{xy} / G_{xx} \\ \Gamma_{xy}^2 &= G_{yy} / G_{y'y'} \end{aligned} \right\}$$



$$y'(t) = \sum_{k=1}^q y_k(t) + n(t)$$

$$Y_k(t) = H_k(t) X_k(t) \quad k=1,2,\dots,q$$

*not measured "clean" output of cycle 2*      *unknown*      *measured input*

$$Y'(t) = \sum_{k=1}^q H_k(t) X_k(t) + N(t)$$

*measured noisy output*      *unknown*      *measured input*      *unknown output noise*

$$X_i^*(t) Y'(t) = \sum_{k=1}^q H_k(t) \cdot X_k(t) X_i^*(t) + X_i^*(t) N(t)$$

$$\left\{ E[X_i^* Y'] = \sum_{k=1}^q H_k E[X_k X_i^*] + E[X_i N] \right\} \text{ not needed.}$$

$$G_{X_i Y'} = \sum_{k=1}^q H_k G_{X_k X_i} + G_{X_i N} = G_{X_i Y'} \quad i=1,2,\dots,q$$

$\sigma$  if  $x_i(t)$  and  $n(t)$  are uncorrelated

$x_i(t)$  and  $n(t)$  are uncorrelated

$$G_{y'y'} = G_{iy'y} = \sum_{k=1}^q H_{ki} G_{ki} \quad i = 1, 2, \dots, q$$

known
unknown
known

linear

This is a set of  $q$  equations for the  $q$  unknowns that are  $(H_1, H_2, \dots, H_q)$

$$G_{y'y'} = \frac{2}{T} Y'^* Y' = \frac{2}{T} \left( \sum_{k=1}^q H_k^* X_k^* + N \right) \left( \sum_{l=1}^q H_l X_l + N \right)$$

$$= \frac{2}{T} \left( \sum_{k=1}^q \sum_{l=1}^q H_k^* H_l G_{kl} + G_{nn} \right)$$

$$+ \frac{2}{T} \left( \sum_{k=1}^q H_k^* \underbrace{G_{kn}}_{\sigma} + \sum_{l=1}^q \underbrace{H_l}_{\sigma} G_{ln} \right)$$

if output noise is uncorrelated with inputs

$$G_{y'y'} = G_{yy} + G_{nn} \quad \text{where } G_{yy} = \sum_{k=1}^q \sum_{l=1}^q H_k^* H_l G_{kl}$$

Now define the multiple coherence of the output and all the inputs as

$$\Gamma_{y:x}^2 \equiv \frac{G_{yy}}{G_{y'y'}} = \frac{G_{y'y'} - G_{nn}}{G_{y'y'}} = 1 - \frac{G_{nn}}{G_{y'y'}} \leq 1$$

end of class  
14

special case  $q=1$ :

$$\Gamma_{y:x}^2 = \frac{G_{yy}}{G_{yy} + G_{nn}} = \frac{|H|^2 \cdot G_{xx}}{G_{yy} + G_{nn}} = \frac{H H^* G_{xx}}{G_{yy} + G_{nn}}$$



Start with

inputs  $x_i$  uncorrelated  
with output noise

$$G_{iy'} = G_{iy} = \sum_{k=1}^q H_k G_{ki} \quad i=1,2,\dots,q$$

measured calculated
ideal linear system
unknown
measured calculated

How to determine a property like  $G_{iy'}$ ? Ex.:  $q=2$

$$G_{iy'} = \frac{2}{T} E[X_i^* Y'] = \frac{2}{T} E[X_i^* (H_1 X_1 + H_2 X_2 + N)]$$

$$= \frac{2}{T} E[H_1 X_i^* X_1] + \frac{2}{T} E[H_2 X_i^* X_2] + \frac{2}{T} E[X_i^* N]$$

$$= \frac{2}{T} H_{11} \underbrace{E[X_i^* X_1]} + \frac{2}{T} H_{12} \underbrace{E[X_i^* X_2]} + 0$$

$$= \hat{G}_{i1} \cdot H_1 + \hat{G}_{i2} H_2$$

read this "expected" value as "ensemble averaged"

$$= G_{i1} H_1 + G_{i2} H_2 \quad \text{for shorthand}$$

So

$$\left. \begin{aligned} G_{1y'} &= G_{11} H_1 + G_{12} H_2 \\ G_{2y'} &= G_{21} H_1 + G_{22} H_2 \end{aligned} \right\} \begin{array}{l} 2 \times 2 \text{ matrix to} \\ \text{solve for} \\ H_1 \text{ and } H_2 \end{array}$$

known
known
known
known

unknown
unknown

Go to p. ~~94~~ 97 → partial coherence



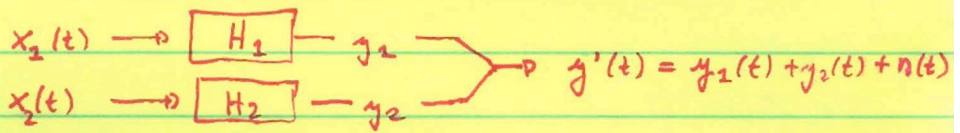
# CLASS #15

example  $q=1$

$$H_1 \cdot G_{11} = G_{1y} = G_{x_1 y}$$

$$\begin{aligned} \Gamma_{y':x}^2 &= \frac{G_{yy'}}{G_{y'y'}} = \frac{|H_1|^2 G_{11}}{G_{y'y'}} = \frac{H_1 H_1^* G_{11}}{G_{y'y'}} \frac{G_{11}}{G_{11}} = \frac{G_{1y} \cdot G_{1y}^*}{G_{y'y'} G_{11}} \\ &= \frac{|G_{1y}|^2}{G_{y'y'} G_{11}} = \frac{|G_{2y'}|^2}{G_{y'y'} G_{11}} = \Gamma_{2y'}^2 = \Gamma_{xy}^2 \end{aligned}$$

example  $q=2$



$$\Gamma_{y':x}^2 = \frac{G_{yy'}}{G_{y'y'}} = \frac{|H_1^* H_1 G_{11} + H_1^* H_2 G_{12} + H_2^* H_1 G_{21} + H_2^* H_2 G_{22}|}{G_{y'y'}}$$

or

$$\begin{aligned} G_{y'y'} \Gamma_{y':x}^2 &= |H_1^* (H_1 G_{11} + H_2 G_{12}) + H_2^* (H_1 G_{21} + H_2 G_{22})| \\ &= |H_1^* G_{1y} + H_2^* G_{2y}| \end{aligned}$$

because

$$G_{1y} = H_1 G_{11} + H_2 G_{12} \quad ; \quad G_{2y} = H_1 G_{21} + H_2 G_{22}$$

which follows from

$$\begin{aligned} G_{1y} &= \frac{2}{T} E[X_1^* Y] = \frac{2}{T} E[X_1^* (H_1 X_1 + H_2 X_2 + N)] \\ &= \frac{2}{T} E[H_1 X_1^* X_1] + \frac{2}{T} E[H_2 X_1^* X_2] + \frac{2}{T} E[X_1^* N] \end{aligned}$$

$$G_{1y'} = \frac{2}{T} H_1 E[X_1^* X_1] + \frac{2}{T} H_2 E[X_2^* X_2] + \frac{2}{T} E[X_1^* N]$$

$$G_{1y'} = H_1 G_{11} + H_2 G_{12} + G_{1n}$$

$G_{2n} = 0$   
↓  
 $= G_{2y}$

$$G_{2y'} = H_1 G_{21} + H_2 G_{22} + G_{2n}$$

$G_{2n} = 0$   
↓  
 $= G_{2y}$

If and only if the output noise is uncorrelated or independent of the input functions, i.e.,  $G_{1n} = G_{2n} = 0$ , can we solve for the transfer functions  $H_1$  and  $H_2$  which after some algebra are

keep for  
p. 99  
homework  
#3 in 2009

$$H_1 = \frac{G_{1y} \left( 1 - \frac{G_{12} G_{2y}}{G_{22} G_{1y}} \right)}{G_{11} (1 - \Gamma_{12}^2)}$$

$$H_2 = \frac{G_{2y} \left( 1 - \frac{G_{21} G_{1y}}{G_{11} G_{2y}} \right)}{G_{22} (1 - \Gamma_{12}^2)}$$

if uncorrelated inputs ← special case  
 $G_{12} = 0$

$$= \frac{G_{1y}}{G_{11}}$$

$$\Gamma_{12}^2 = \Gamma_{x_1, x_2}^2 = \frac{|G_{12}|^2}{G_{11} G_{22}}$$

if inputs are not correlated  
 $G_{12} = 0$

$$= \frac{G_{2y}}{G_{22}}$$

thing is true only for the special case of uncorrelated inputs

which gives  
if inputs are not correlated  
 $G_{12} = 0 \rightarrow G_{ij} = H_i G_{ij}$

$$\Gamma_{y':x}^2 = \frac{|H_1^* G_{1y}|}{G_{y'y'}} + \frac{|H_2^* G_{2y}|}{G_{y'y'}} = \frac{G_{1y}^* G_{1y}}{G_{11} G_{y'y'}} + \frac{G_{2y}^* G_{2y}}{G_{22} G_{y'y'}} = \frac{G_{y'y}}{G_{y'y'}}$$

$$= \frac{|G_{1y}|^2}{G_{11} G_{y'y'}} + \frac{|G_{2y}|^2}{G_{22} G_{y'y'}} = \Gamma_{1y'}^2 + \Gamma_{2y'}^2$$

What to do if input are related?