

Analysis of spatial data \rightarrow Map Analysis

ref. Davis, J.C. (1986). Statistics and data analysis in geology.

John Wiley and Sons, New York, NY, 646 pp.

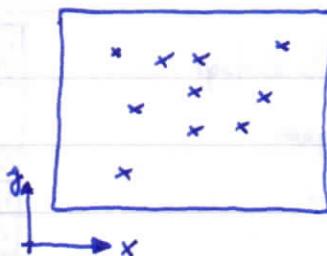
very good and readable summary with many examples
 and practical applications of both temporal (somewhat
 sketchy) and spatial (much detail) analysis techniques

1 Introduction



geography

(b)



spatial data

maps of properties

"topography", vertical

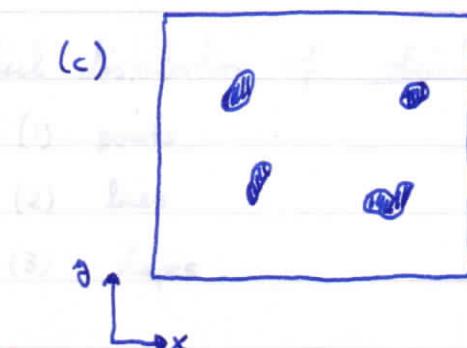
elevations

salinity

weather maps

 $z = z(x, y)$ geology
mining

(c)



spatial data

shapes

maps of the presence/

absence of a

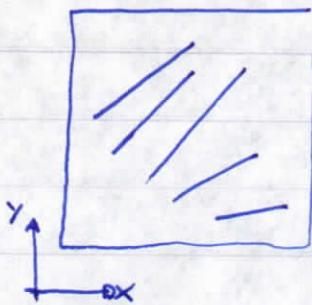
property such as

- mineral deposits

- distribution of ice

- plankton patchiness

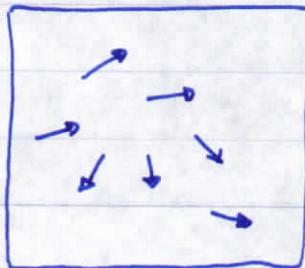
(d)



spatial data

- maps of orientations
such as due to
- fault lines
 - location of fronts
 - leads in ice
 - ripples of sand/sediment

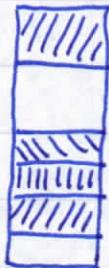
(e)



spatial data

- maps of directions
- wind, velocity
 - striations of glaciers
 - river channels in a watershed

(f)



spatial data

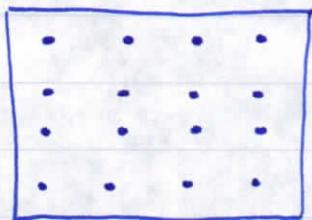
- map of sequences of properties
- sediment core
 - ice core

⇒ spatial distribution of objects that are

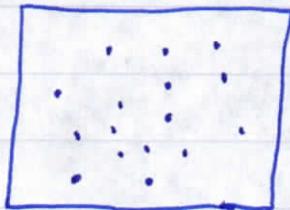
- (1) points
- (2) lines
- (3) shapes

wide range of techniques ; I'm just skimming the surface

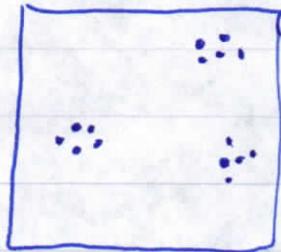
Distribution of "points" in space



regular grid



randomly scattered pts



clusters of pts.

Def.: Uniform density of pts in all subareas of the same size and shape is the same everywhere

Regular points are placed on a grid of some sort

Reliability of contour maps depends upon density AND uniformity of the observations. Often, the "contouring" is a 2 step process:

- (a) generate a regular grid from quasi-uniform data → spatial interpolation
- (b) interpolate contour lines through the regular grid → - o -

How to test (quantitatively) for "uniformity" and "randomness"?

construct a "statistic", e.g.,

$$\sum_{i=1}^N \frac{(O-E)^2}{E} = \chi^2_{N-2}$$

O - observed # of pts in subarea

E - expected # of pts in subarea

$$E = \frac{\text{total # of data}}{\# \text{ of subareas } N}$$

and test the hypothesis that data is evenly distributed

	Hypothesis correct	Hypothesis incorrect
Hypothesis is accepted	correct decision	type II error β
Hypothesis is rejected	type I error α	correct decision

probability of type I error

- specify α , which is the "level of significance"
- formulate hypothesis in such a way that you hope to reject it

"... statistical tests cannot say what IS, but only what IS NOT..."

1. Hypothesis (to be rejected, hopefully) : data is unevenly distributed

2. significance level : $\alpha = 5\%$

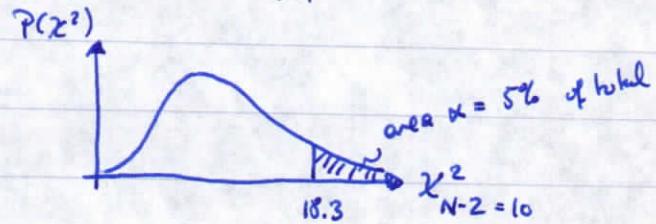
3: the statistic : $\chi^2_{N-2} = \sum_{i=1}^N \frac{(O-E)^2}{E}$

Hypothesis is rejected if $\chi^2_{N-2} = \sum_{i=1}^N \frac{(O-E)^2}{E} \leq \chi^2_{N-2, \alpha}$

.	.	.	.
.	.	.	.
:	:	:	:
:	:	:	:
:	:	:	:

quadrant i	0	(0-E ²)/E	$E = 123/12 \approx 10$
1	20	0	
2	5	2.6	
3	5	2.6	
:	:	:	
$N = 12$	<u>8</u>	<u>0.48</u>	
	<u>123</u>	$\chi^2 = 15.23 = \sum_{i=1}^N (0-E)^2/E$	

$$\chi^2_{N-2; \alpha=0.05} = 18.3$$



"Goodness of fit" leads us to conclude that the data is uniformly distributed

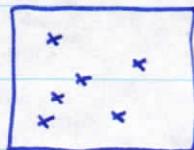
BUT depends upon the scale, i.e., the size of the quadrant \rightarrow scale dependence

BUT random distributions can be uniform \rightarrow further test necessary to know more

to remove the "scale dependence" do a

Nearest - Neighbor Analysis

Contouring and Gridding



discrete measurement

$$z_i = z_i(x_i, y_i)$$

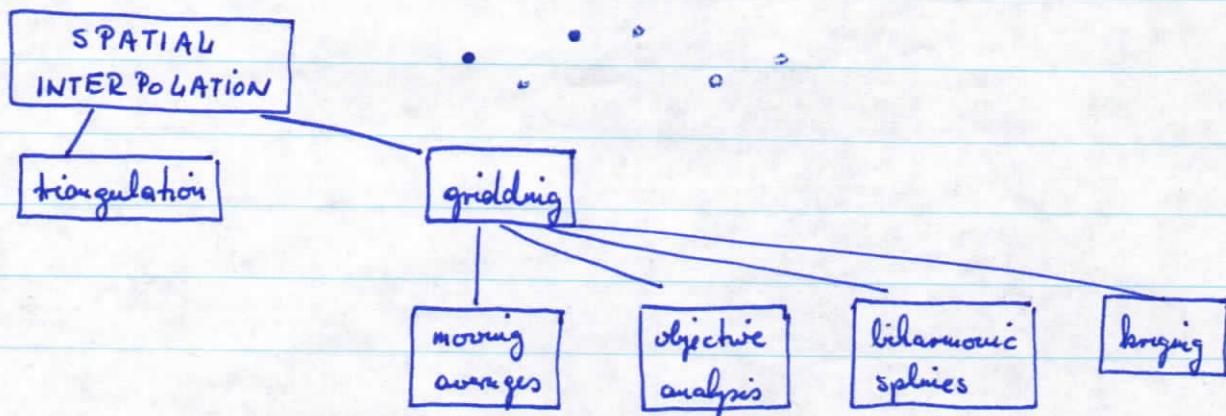


continuous function

$$z_i = z_i(x, y)$$

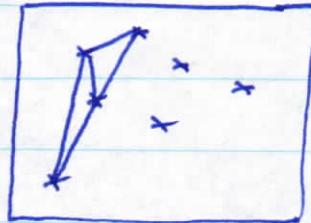
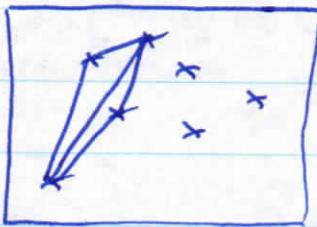
spatial interpolation: it's still more an art than a science
even (or especially) if done by a computer

- always depict on the contour map where your measurements are located
- indicate what your measurement errors are
- indicate how the data are honored



Triangulation :

60 in
70 in



not uniquely defined

need excessive interactions to select an "optimal" set of triangles

"optimal" :

- near to equilateral as possible
- maximum height
- largest leg as short as possible

80 in

Delaunay triangulations:

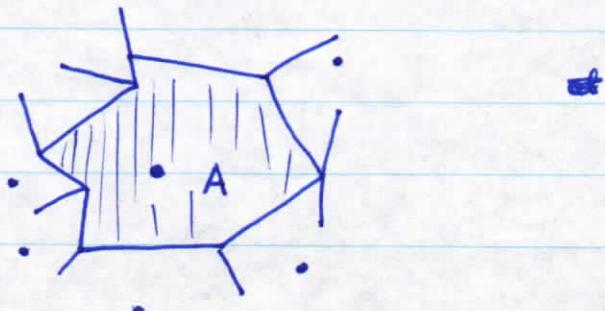
- uniquely defined
- longest sides as short as possible
- triangles are as equangular as possible

connects points in a triangular network that are
Thiessen neighbors.

Thiessen polygon

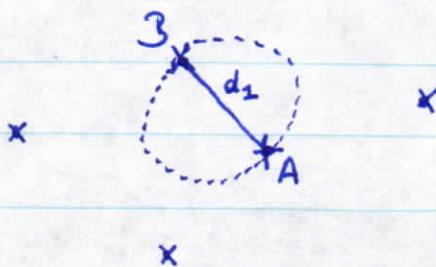
=

all points within are
closer to A than
to any other point



Determine the Thiessen neighbors

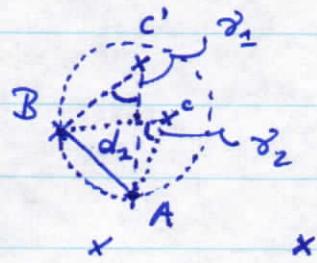
Step 1:



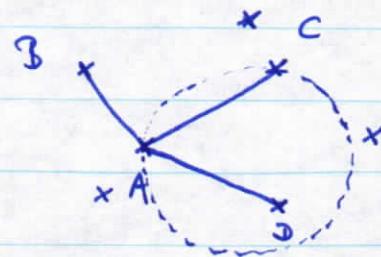
B is a neighbor if no pts are within the circle of diameter d_1

Step 2: construct a circle with $d_2 > d_1$ that has A and B on its perimeter.

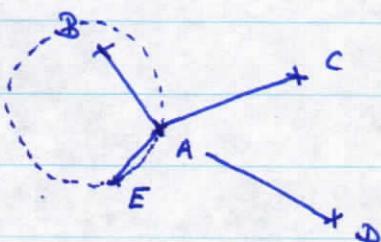
The pt. neighbor is with "largest" d_2 :



Step 3 move on clockwise, i.e., construct successively longer circles that have A and the last neighbor on the perimeter



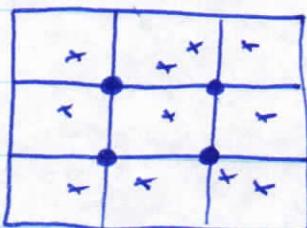
continue until you're back to pt. B as the closest neighbor



McGillagh, T.J. (1981). Creation of smooth contours over irregularly distributed local surface patches. Geographical Analysis, 13, 51-63.

Gridding

(a) Weighted (moving) averages



- measurements of $z_i(x_i, y_i)$
- grid nodes (\hat{x}_k, \hat{y}_k)

for each node k find a set of n nearest data to be used in forming an average

OR

for each node k find a set of data within a fixed radius (neighborhood) to form an average

average the found data and thus define $\hat{z}_k(\hat{x}_k, \hat{y}_k)$ at node

$$\hat{z}_k = \sum_{i=1}^n z_i$$

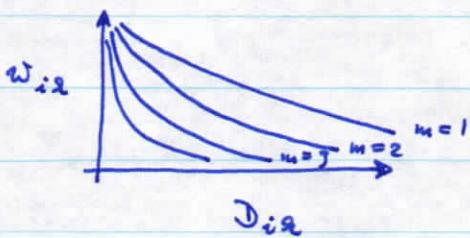
better yet, assign weights, e.g., weights proportional to the distance of the data (x_i, y_i) to the grid location (\hat{x}_k, \hat{y}_k)

$$D_{ik} = \sqrt{(\hat{x}_k - x_i)^2 + (\hat{y}_k - y_i)^2}$$

and the weighted average is

$$\hat{z}_k = \frac{\sum_{i=1}^n z_i / D_{ik}}{\sum_{i=1}^n 1 / D_{ik}} = \sum_{i=1}^n w_{ik} z_i \quad w_{ik} = \frac{1}{\sum_{i=1}^n D_{ik}}$$

where m is an arbitrary power



How to search for the n points to be included in the interpolation?

~~Distance~~ 1

three points

are all equi-
distance from
node

$A \times^{1/3}$

•

$\frac{1}{3} \times \quad \times \frac{1}{3}$

B

C

$A \quad A'$

$$\frac{1}{4} + \frac{1}{4} = \frac{1}{2}$$

•

x

x

$\frac{1}{4}$

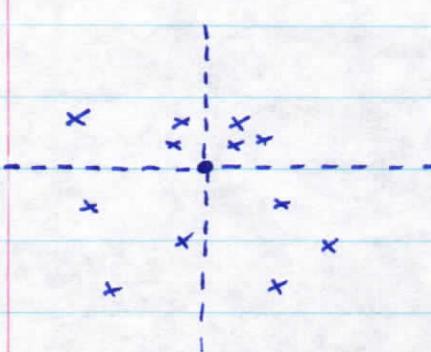
≈ 1

x
B
 ≈ 0

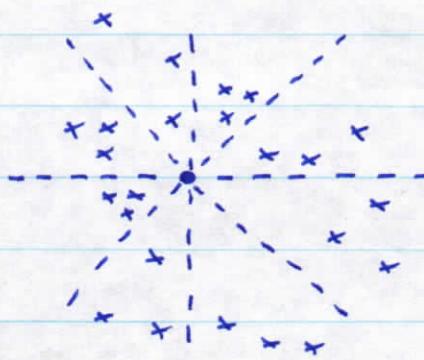
x
C
 ≈ 0

⇒ spatial arrangement important

⇒ search in angular segments, i.e.



quadrant search



octant search

Alternatives to weighted averaging

fit a least-square model locally, e.g.,

$$\hat{z}_k = a + b \hat{x}_k + c \hat{y}_k \quad \text{linear}$$

$$+ d \hat{x}_k^2 + e \hat{y}_k^2 + f \hat{x}_k \hat{y}_k \quad \text{quadratic}$$

$$\dots$$

$$\vdots$$

find coefficients by minimizing

$$\Sigma (a, b, \dots) = \sum_{i=1}^n [z_i - (a + b x_i + c y_i + \dots)]^2$$

This referred to as TREND SURFACE ANALYSIS

other "models" are possible, e.g.,

biharmonic splines (see notes on harmonic analysis in space)

which mathematically is equivalent to the constraint of finding
a surface with MINIMUM CURVATURE over the
domain

comment
below

McIntosh, P.C. (1990). Oceanographic data interpolation: objective
analysis and splines. *J. Geophys. Res.*, 95, 13529-13541

biharmonic splines \longleftrightarrow minimum curvature

semi-norm
interpolation

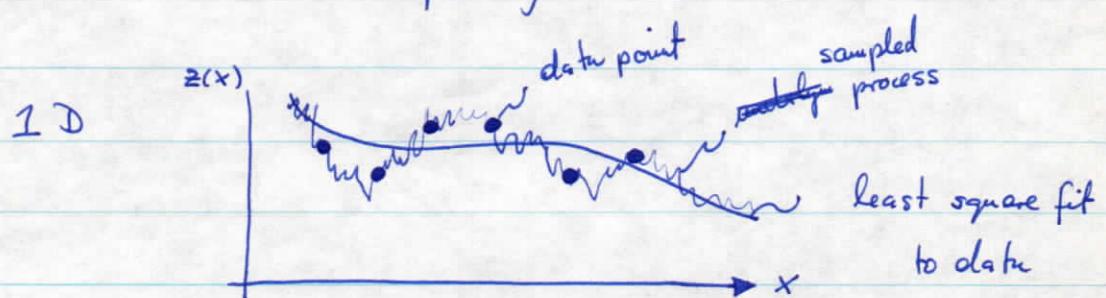
$$\|f(x, y)\| = \iint f_x^2 + f_y^2 + f_{xx}^2 + f_{xy}^2 + f_{yy}^2 dx dy$$

objective analysis
(prescribe error
and signal statistics)

norm
interpolation

$$\|f(x, y)\| = \iint f^2 + f_x^2 + f_y^2 + f_{xx}^2 + f_{xy}^2 + f_{yy}^2 dx dy$$

COMMENT: Note the complexity



the error at sampling points
does NOT have to
represent the error field correctly !