

CLASS #1

- 0. Introduce myself and ask students to do the same
- 1. Hand out revised Course Outline and briefly discuss it
- 2. Computer exercises: Numerical Recipes OK  
 IMSU OK  
 "Need to see CODE"

Def.: Time Series a collection or sequence of numbers that represent the state of any system as a function of time (or space or any other "ordering" independent variable).

ex.1: Can be complex, i.e.,  $b = a + j b$   $j = \sqrt{-1}$   
real complex parts

Can be scalars like temperature or sealevel

Can be vectors like ocean current  $\vec{u} = (u_{east}, v_{north}, w_{up})$

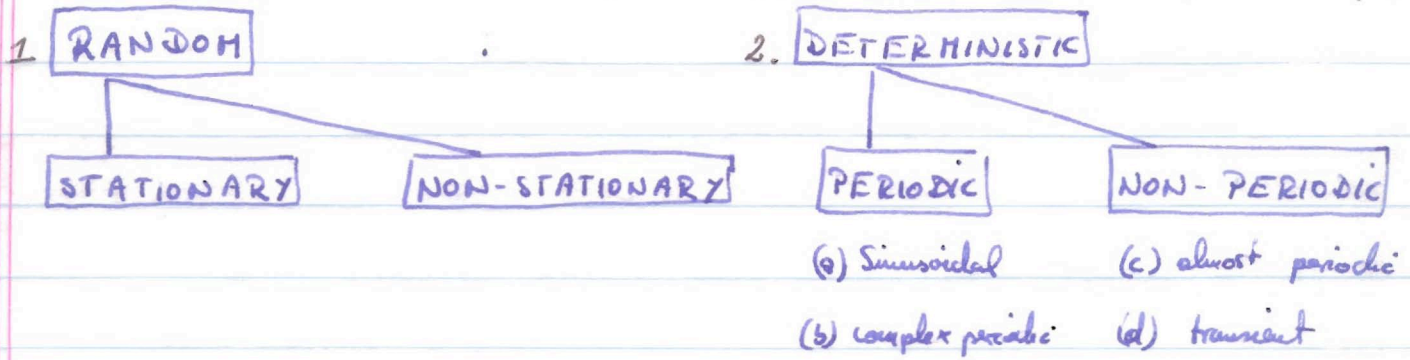
Can be ~~vectors~~ <sup>matrices</sup> like spatial patterns  $u_{east} = \begin{cases} u_{east}(x_1, y_1, t) \\ u_{east}(x_2, y_2, t) \\ u_{east}(x_3, y_3, t) \end{cases}$

ex.2: discrete series  $x(t_i)$   $i = 1, 2, 3, \dots$   
 continuous  $x(t)$

ex.3: deterministic, i.e., can in principle be predicted into the future  
 random (stochastic), i.e., cannot be predicted into the future without stating probabilities (weather)

# Ensemble, auto-correlation, stationarity, ergodicity

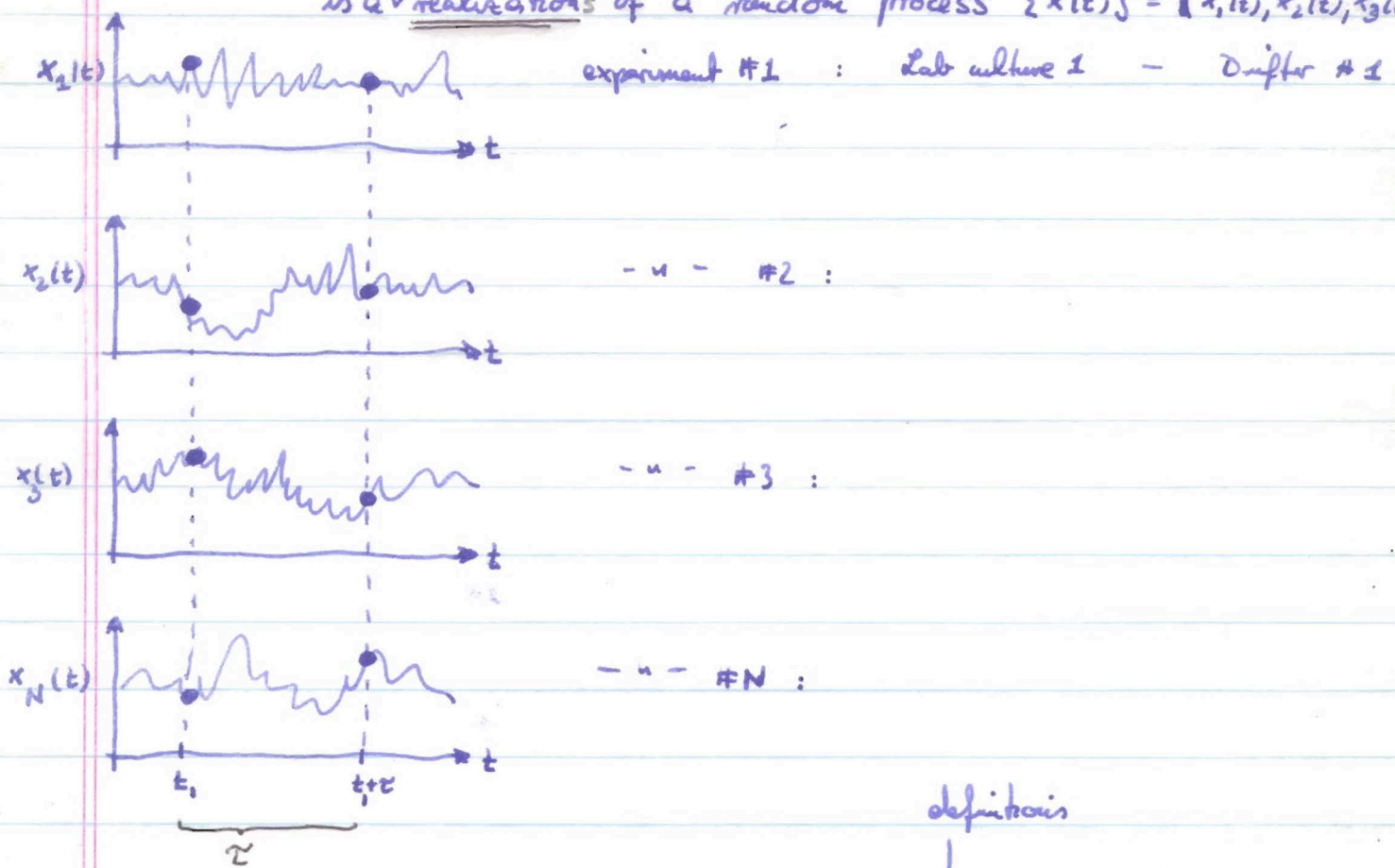
2  
begin class #2/99



## 1. RANDOM data

Ensemble: Needs to be clearly defined; "replica"; repetitions  
 is a <sup>set of</sup> realizations of a random process  $\{x(t)\} = \{x_1(t), x_2(t), x_3(t), \dots\}$

climate change  
numerical modeling



definitions

Mean over ensembles:  $\mu_x(t_2) \equiv \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^N x_k(t_2)$

auto-correlation:  $R_{xx}(t_2, t_2 + \tau) \equiv \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^N x_k(t_2) \cdot x_k(t_2 + \tau)$

If

$\mu_x(t) = \text{const.}$  , i.e., universal mean holds at all times

and

$R_{xx}(t, t+\tau) = R_{xx}(\tau)$  , i.e., auto-correlation does not depend on the start times

then

the process  $\{x(t)\}$  is said to be stationary.

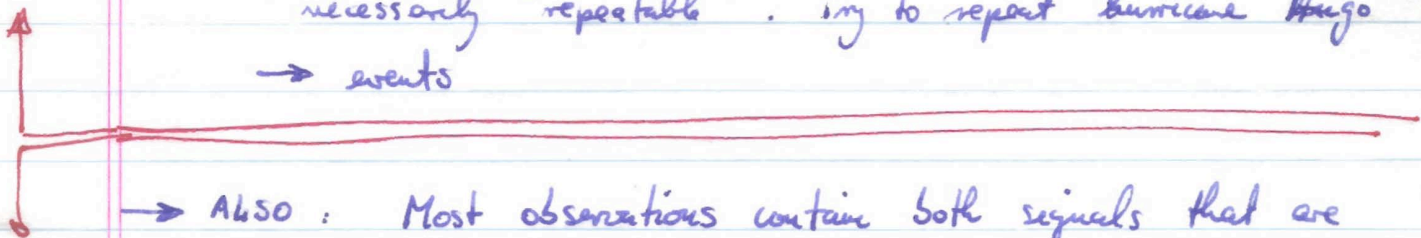
→ Now, who can afford to <sup>redo exactly</sup> sample the same experiment every so often?

If it is at possible to repeat the experiment it is usually prohibitive expensive.

Many naturally occurring systems (like weather, oceans) are not necessarily "repeatable". Try to repeat hurricane "Hugo"  
→ events

#1

Sept. 5



#2

Sept. 8

→ ALSO: Most observations contain both signals that are deterministic and random, i.e.,

$$\text{MEASUREMENT} = \text{SIGNAL} + \text{NOISE}$$

try to separate the two (it ain't easy)

→ Assume that the observed process  $\{x(t)\}$  is ERGODIC