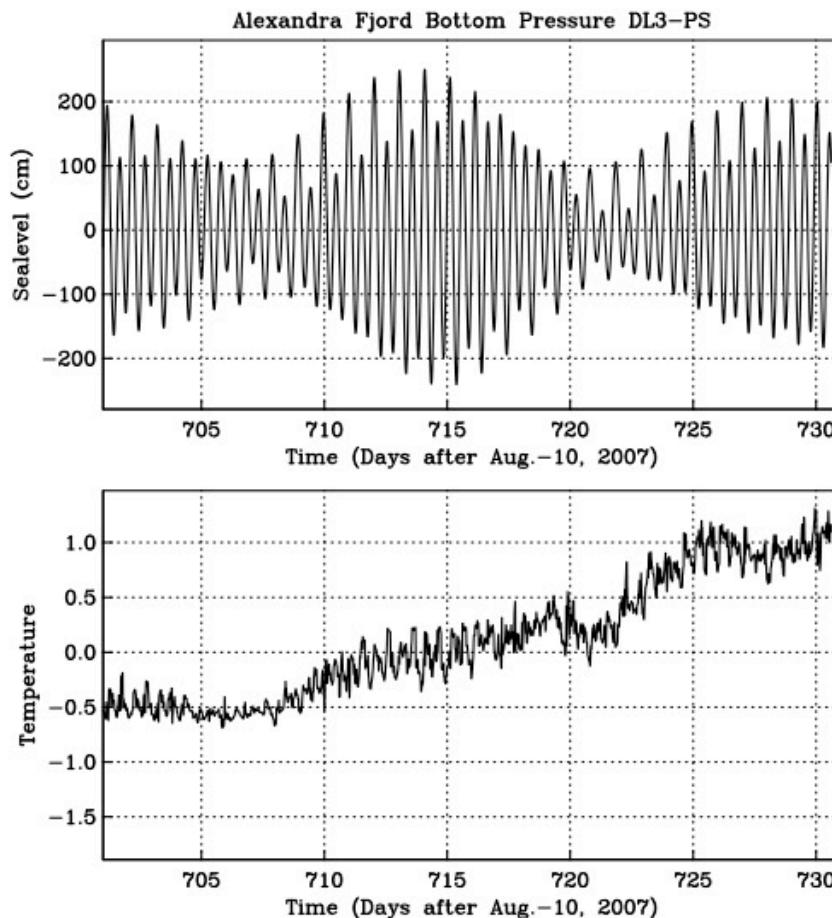


Scalar Time Series Data



Deterministic Data

can be predicted into the future

Example: Tides

Stochastic or Random Data

cannot be predicted into the future
without stating probabilities

Example: Weather

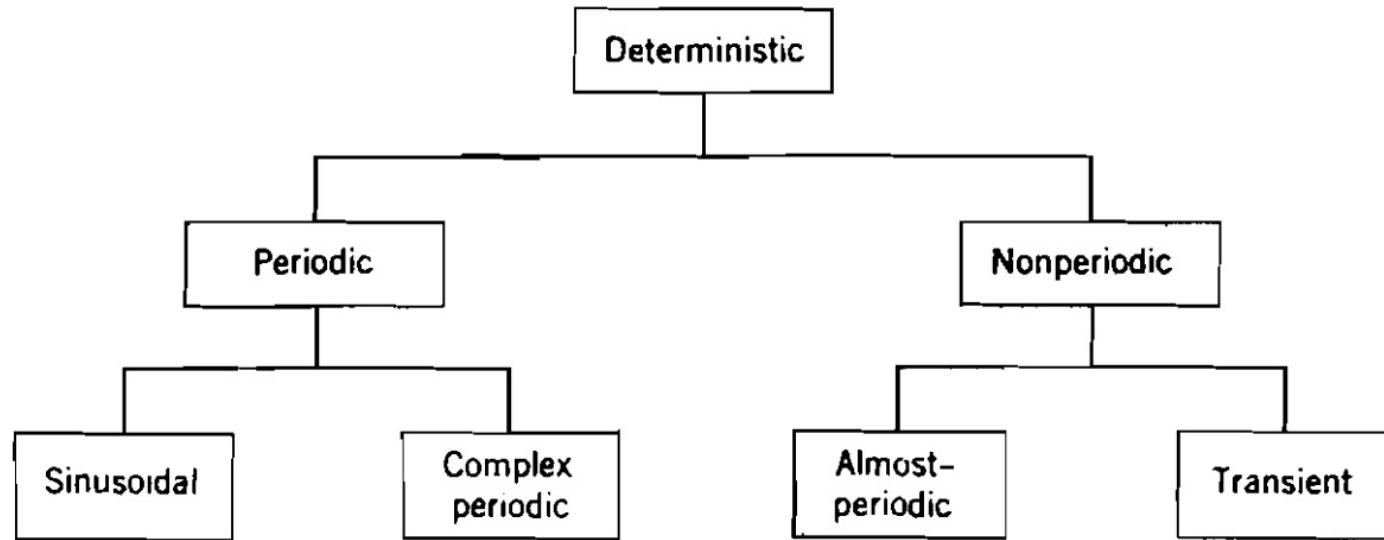


Figure 1.2 Classifications of deterministic data.

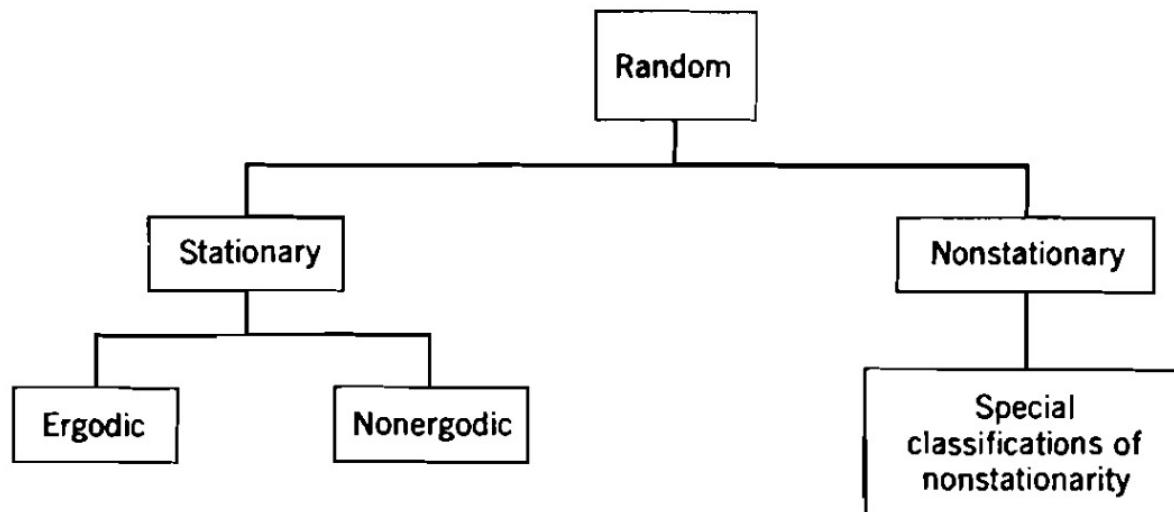


Figure 1.9 Classifications of random data.

Time Domain \Leftarrow Frequency Domain

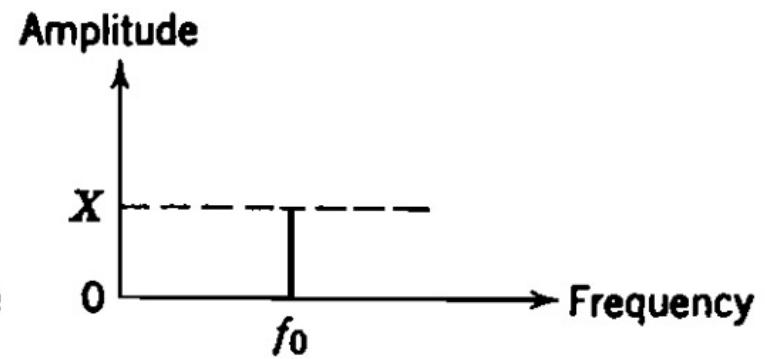
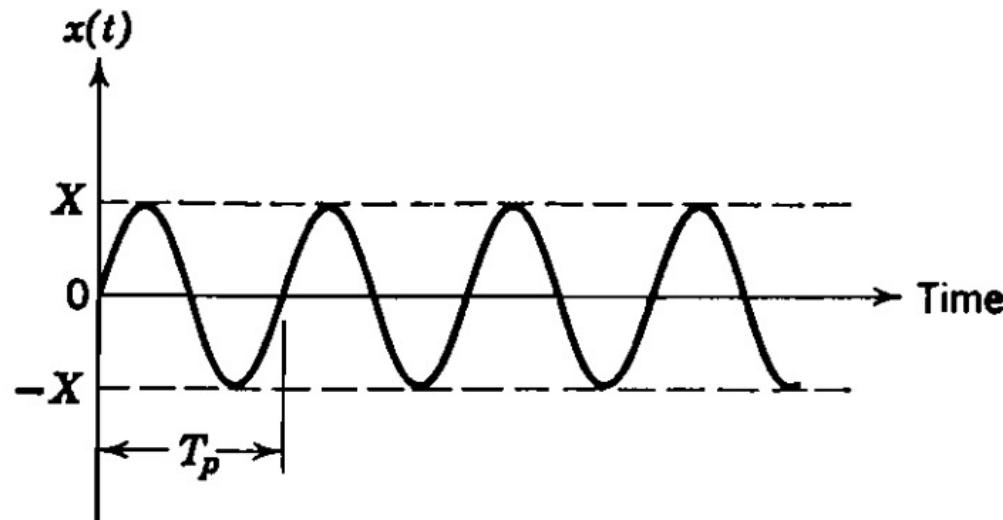
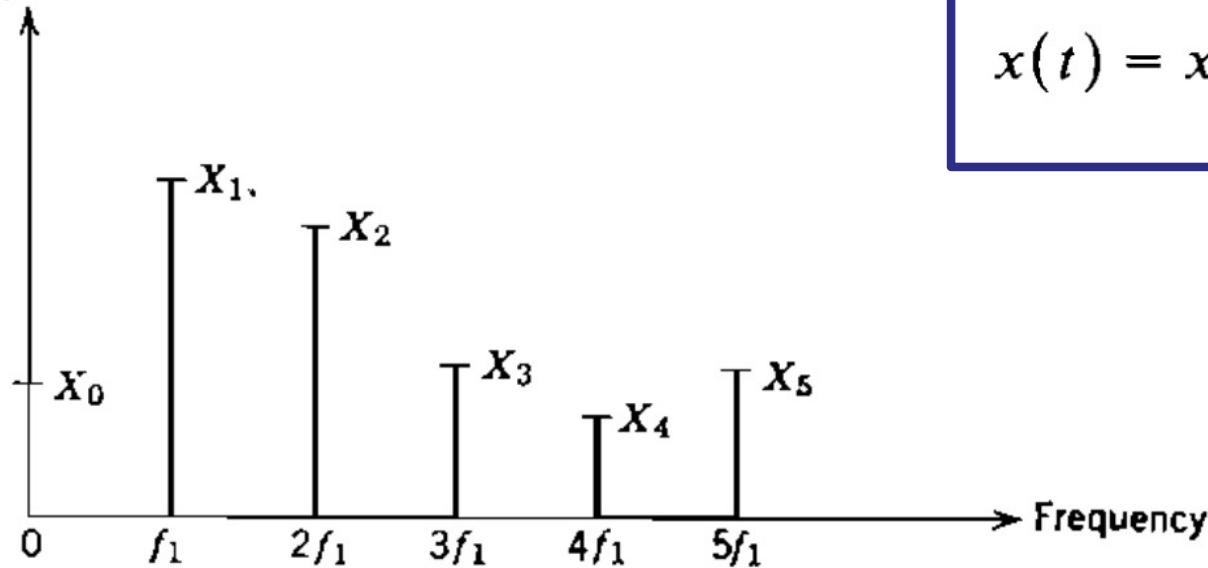


Figure 1.3 Time history and spectrum of sinusoidal data.

$$T_p = 1 / f_0 \quad \text{Period}$$

$$f_0 = 1 / T_p \quad \text{Frequency}$$

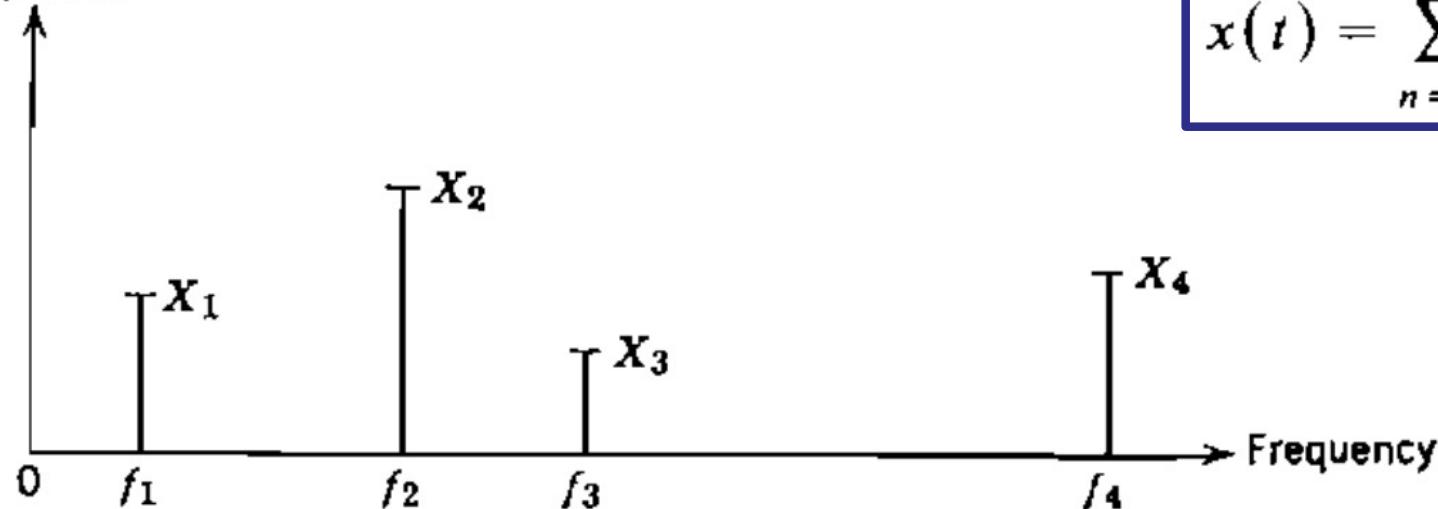
Amplitude



$$x(t) = x(t \pm nT_p) \quad n = 1, 2, 3, \dots$$

Figure 1.4 Spectrum of complex periodic data.

Amplitude



$$x(t) = \sum_{n=1}^{\infty} X_n \sin(2\pi f_n t + \theta_n)$$

Figure 1.5 Spectrum of almost-periodic data.

Time Domain

$$x(t) = \begin{cases} A e^{-at} & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$x(t) = \begin{cases} A e^{-at} \cos bt & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$x(t) = \begin{cases} A & c \geq t \geq 0 \\ 0 & c < t < 0 \end{cases}$$

Frequency Domain

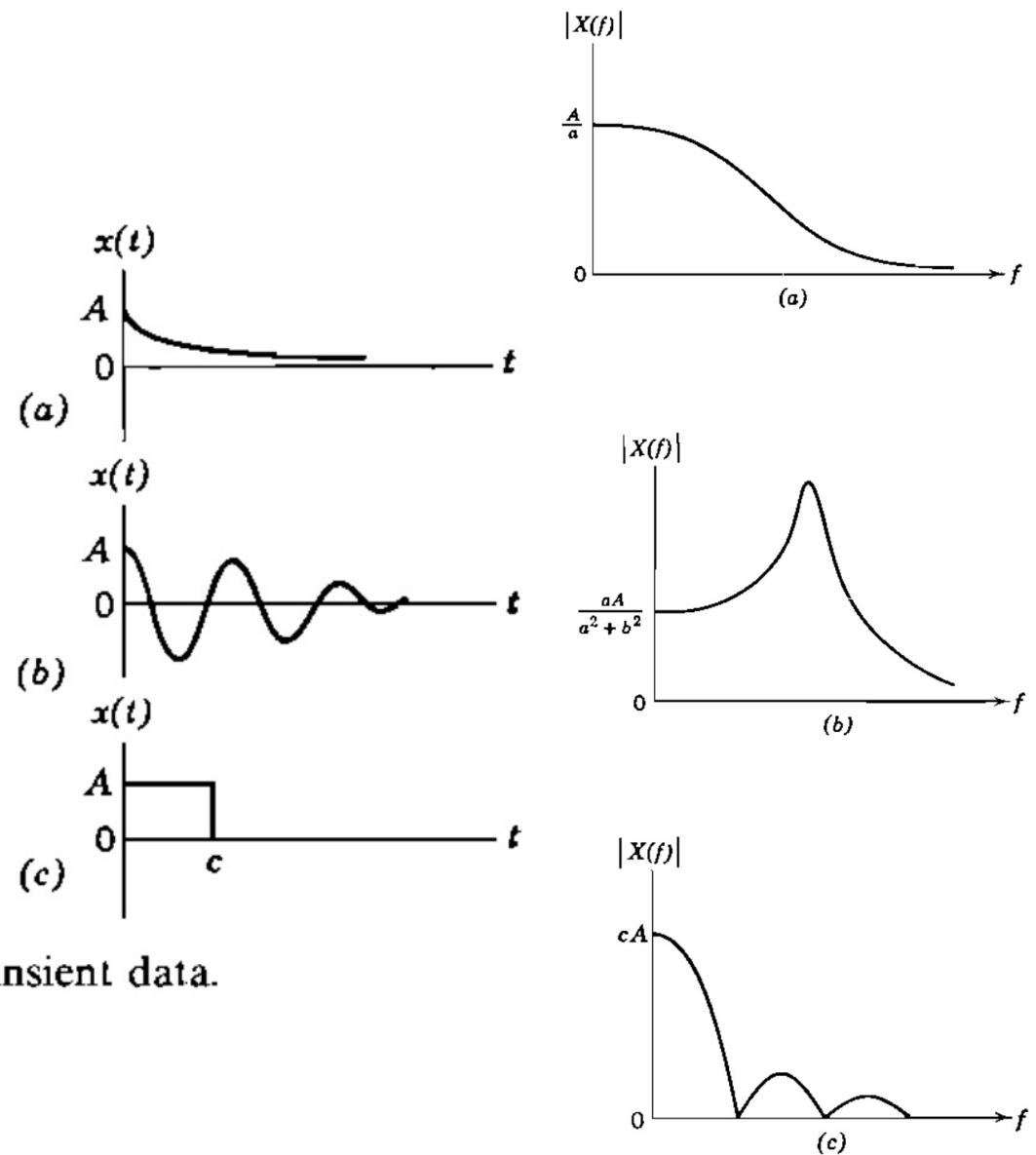


Figure 1.6 Illustrations of transient data.

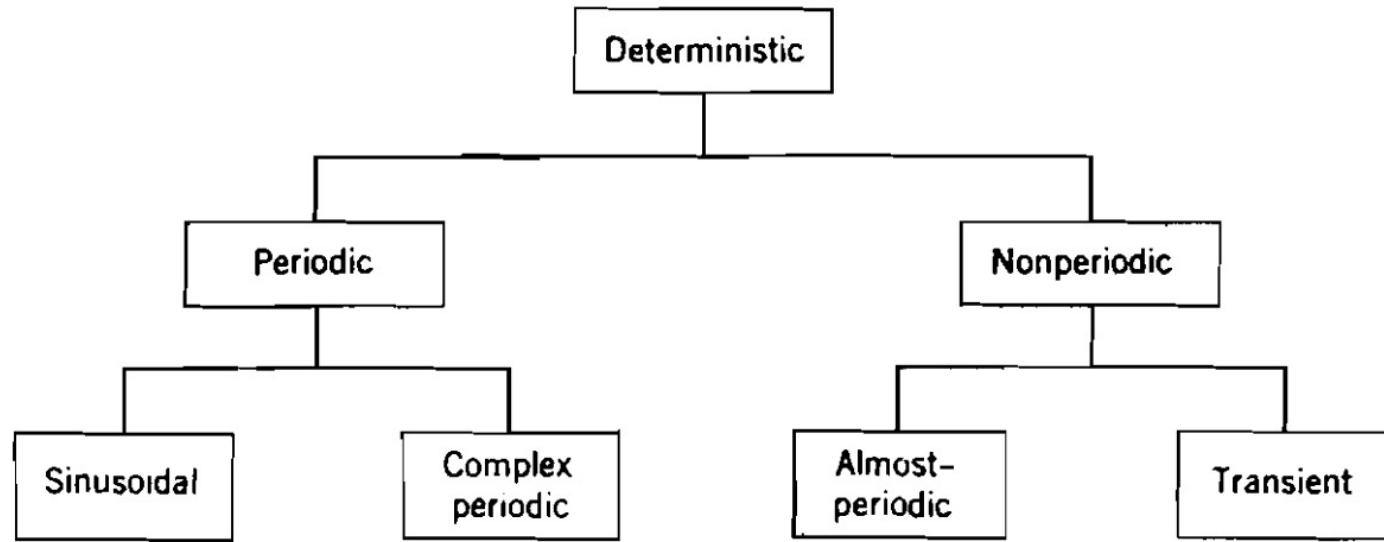


Figure 1.2 Classifications of deterministic data.

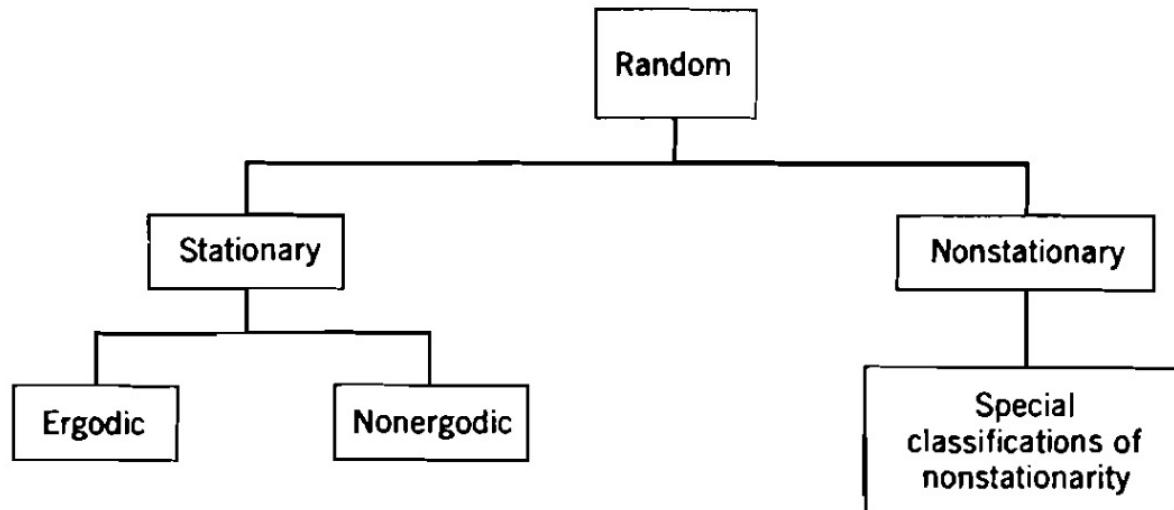


Figure 1.9 Classifications of random data.

Ensembles are a set of realizations $x_i(t)$ of a **random process** $\{x(t)\}$

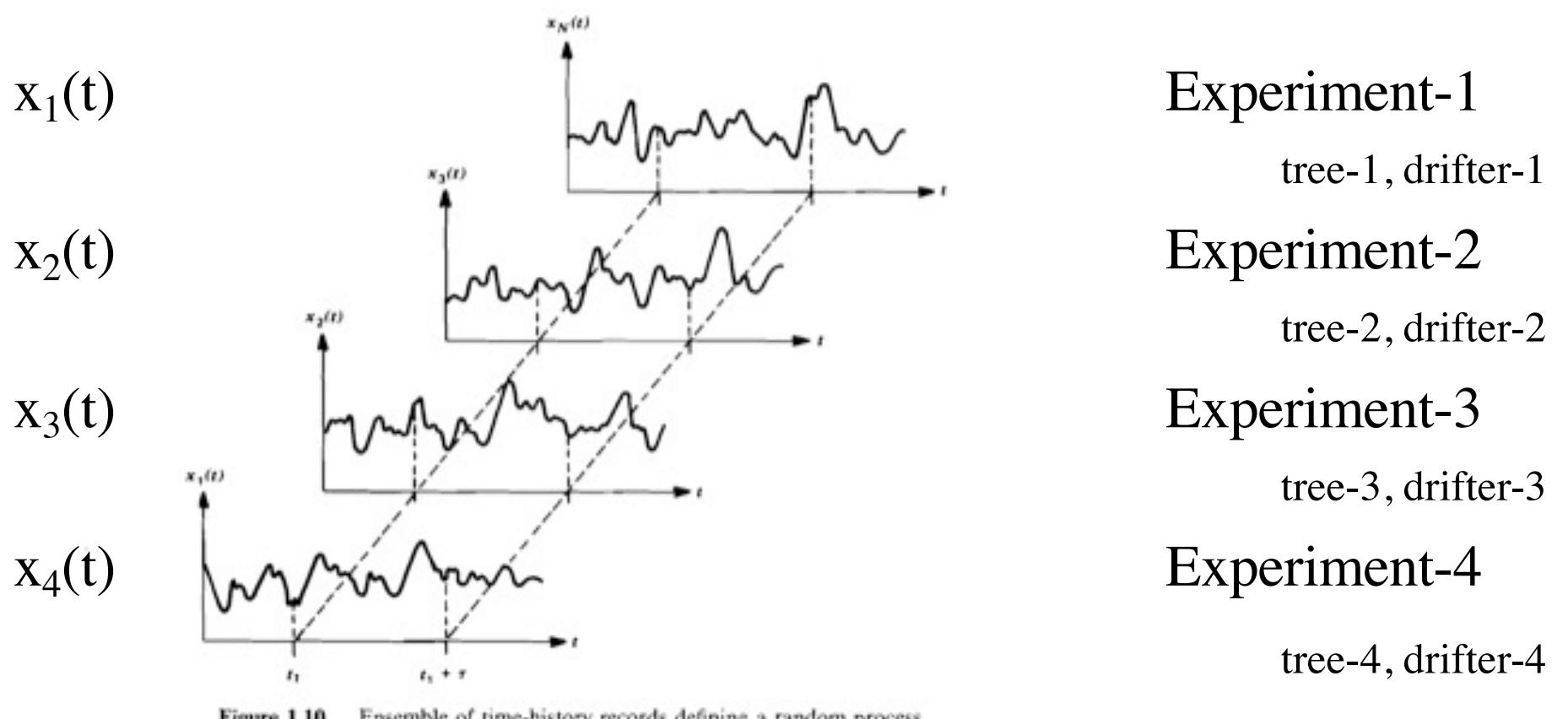


Figure 1.10 Ensemble of time-history records defining a random process.

t

$t+\tau$

Time t and lag τ

Stationary Random Process

Define: Mean over all Ensembles $\mu_x(t)$

$$\mu_x(t_1) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^N x_k(t_1)$$

Define: Auto-Correlation $R_{xx}(t, t+\tau)$

$$R_{xx}(t_1, t_1 + \tau) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{k=1}^N x_k(t_1) x_k(t_1 + \tau)$$

Stationary Random Process

Define: Mean over all Ensembles $\mu_x(t)$

Define: Auto-Correlation $R_{xx}(t,t+\tau)$

If

$$\mu_x(t) = \text{constant}$$

and

$$R_{xx}(t,t+\tau) = R_{xx}(\tau)$$

then

random process $\{x\}$ is stationary.

Ergodic Random Process

Stationary process for which the time average from a single realization can replace an ensemble average.

Go to Lecture Notes or SmartBoard to formalize

MEASUREMENT

=

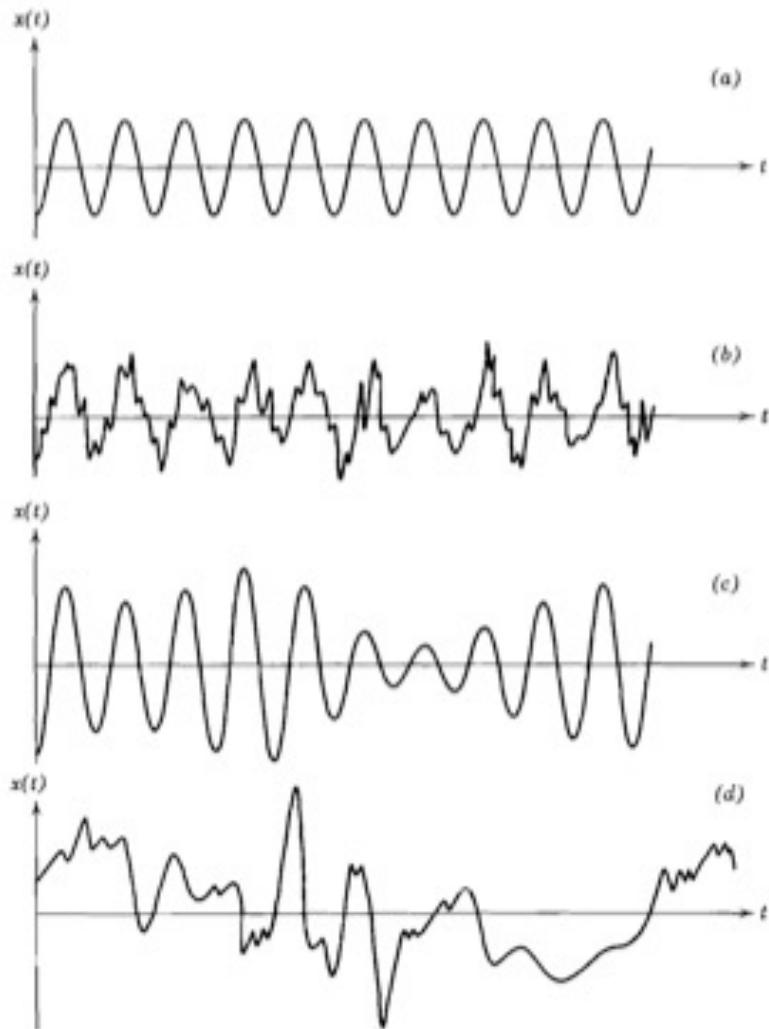
SIGNAL

+

NOISE

How to separate?

Qualities of time series: (time domain)



Sine wave

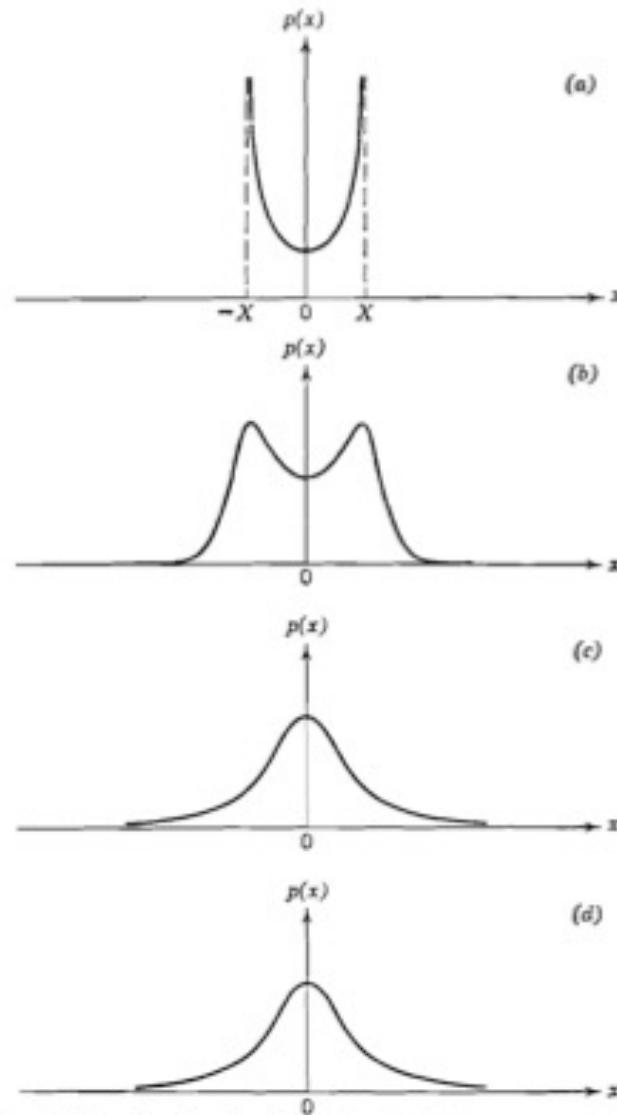
Sine wave plus random noise

Narrow-band random noise

Wide-band random noise

Figure 1.11 Four special time histories. (a) Sine wave. (b) Sine wave plus random noise. (c) Narrow-band random noise. (d) Wide-band random noise.

Probability Density Functions: (histograms)



Sine wave

Sine wave plus random noise

Narrow-band random noise

Wide-band random noise

Figure 1.12 Probability density function plots. (a) Sine wave. (b) Sine wave plus random noise. (c) Narrow-band random noise. (d) Wide-band random noise.

Auto-correlation functions (time domain)

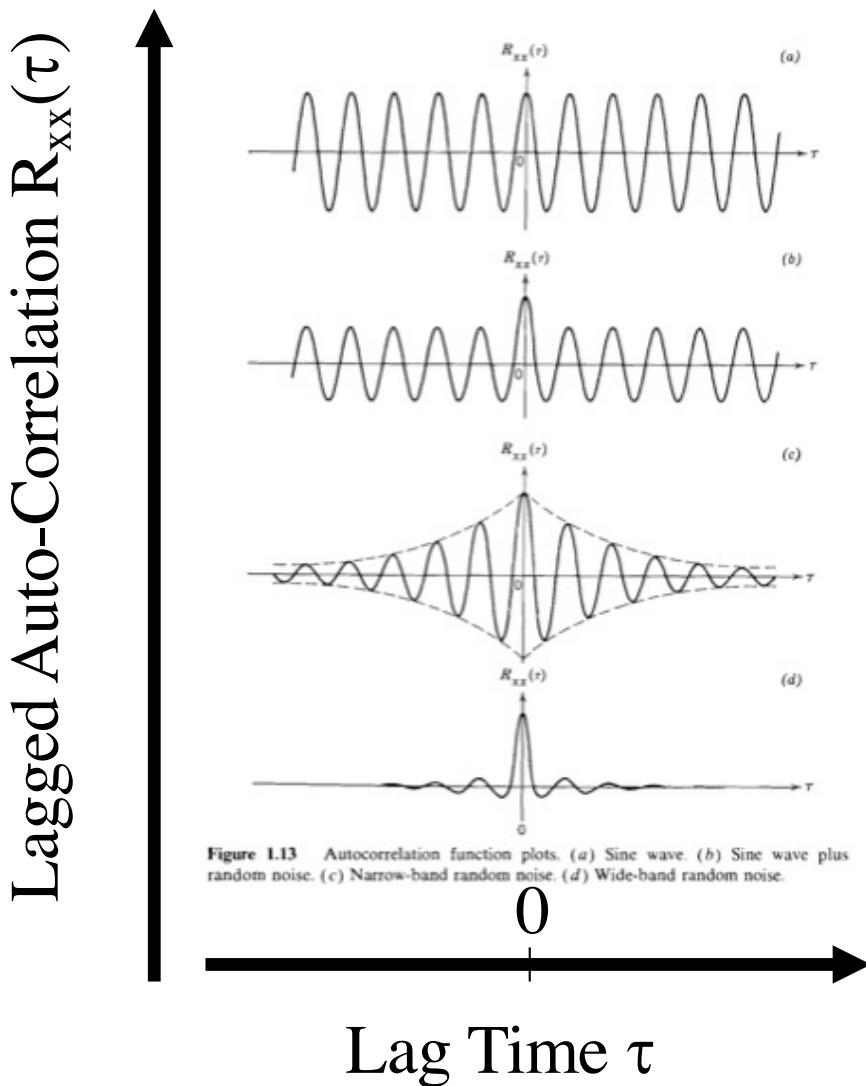


Figure 1.13 Autocorrelation function plots. (a) Sine wave. (b) Sine wave plus random noise. (c) Narrow-band random noise. (d) Wide-band random noise.

Sine wave

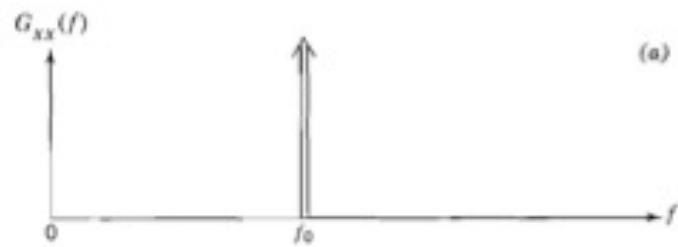
Sine wave plus random noise

Narrow-band random noise

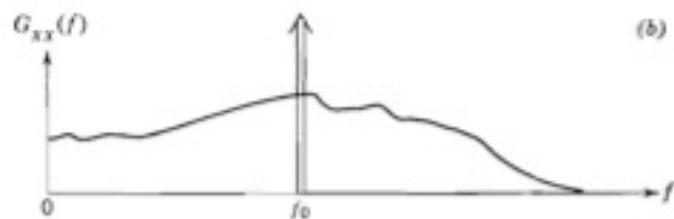
Wide-band random noise

Auto-spectral Density

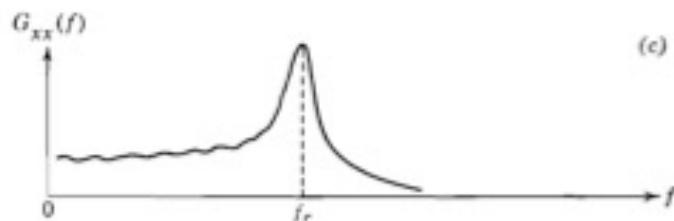
(frequency domain)



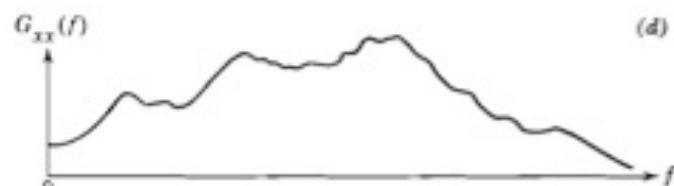
Sine wave



Sine wave plus random noise



Narrow-band random noise



Wide-band random noise

Figure 1.14 Autospectral density function plots. (a) Sine wave. (b) Sine wave plus random noise. (c) Narrow-band random noise. (d) Wide-band random noise.